

**PAT-NO:** JP361122711A  
**DOCUMENT-IDENTIFIER:** JP 61122711 A  
**TITLE:** TEACHING DEVICE OF ROBOT  
**PUBN-DATE:** June 10, 1986

**INVENTOR-INFORMATION:**

**NAME** **COUNTRY**  
NAKAMURA, YOSHITERU

**ASSIGNEE-INFORMATION:**

**NAME** **COUNTRY**  
FUJITSU LTD N/A

**APPL-NO:** JP59243312  
**APPL-DATE:** November 20, 1984

**INT-CL (IPC):** G05B019/42 , B25J009/22 , B25J013/08

**US-CL-CURRENT:** 318/568.13 , 318/568.25

**ABSTRACT:**

**PURPOSE:** To teach a robot easily for a short period by controlling three light emitting sources and two position detectors periodically to control the operation of detected information and the robot.

**CONSTITUTION:** A position detector PSD camera controller PCC controls the position detecting operations of position detectors PSD1, PSD2 and the light emitting operations of light emission diodes LEDs 1~3 periodically, and also calculates the position and posture of a glove G on the basis of the detected information by the position detectors PSD1, PSD2. An A/D converter AD converts these calculated values into digital values and inputs the digital values to a robot controller RC to apply commands for the position, posture and the opening width H of the hand to the robot R on the basis of a command outputted from a control box CB.

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